# ZHENYU WEI

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## EDUCATION

**University of North Carolina at Chapel Hill**, USA  Aug. 2025 - Present
*Ph.D. in Computer Science*  **Advisor:** Prof. Mingyu Ding

**Shanghai Jiao Tong University**, China  Sep. 2021 - Jun. 2025
*B.Eng. in Computer Science (Zhiyuan Honor Degree)*  **GPA:** 4.0/4.3

## PUBLICATIONS

[8] **One Hand to Rule Them All: Canonical Representations for Unified Dexterous Manipulation**
***Zhenyu Wei**, Yunchao Yao, Mingyu Ding*

[7] **When Vision Overrides Language: Evaluating and Mitigating Counterfactual Failures in VLAs**
*Yu Fang, Yuchun Feng, Dong Jing, Jiaqi Liu, Yue Yang, **Zhenyu Wei**, Daniel Szafir, Mingyu Ding*

[6] **Mixture of Horizons in Action Chunking**
*Dong Jing, Gang Wang, Jiaqi Liu, Weiliang Tang, Zelong Sun, Yunchao Yao, **Zhenyu Wei**, Yunhui Liu, Zhiwu Lu, Mingyu Ding*

[5] **RL-100: Performant Robotic Manipulation with Real-World Reinforcement Learning**
*Kun Lei\*, Huanyu Li\*, Dongjie Yu\*, **Zhenyu Wei\***, Lingxiao Guo, Zhennan Jiang, Ziyu Wang, Shiyu Liang, Huazhe Xu*

[4] **TelePreview: A User-Friendly Teleoperation System with Virtual Arm Assistance for Enhanced Effectiveness**
*Jingxiang Guo\*, Jiayu Luo\*, **Zhenyu Wei\***, Yiwen Hou, Zhixuan Xu, Xiaoyi Lin, Chongkai Gao, Lin Shao*
**ICRA 2025 @ Human-Centric Multilateral Teleoperation Workshop (Best Paper Award)**

[3] **MetaFold: Language-Guided Cross-Category Garment Folding Framework via Trajectory Generation and Foundation Model**
*Haonan Chen\*, Junxiao Li\*, Ruihai Wu, Yiwei Liu, Yiwen Hou, Zhixuan Xu, Jingxiang Guo, Chongkai Gao, **Zhenyu Wei**, Shensi Xu, Jiaqi Huang, Lin Shao*
**IROS 2025 (Oral)**

[2] $\mathcal{D}(\mathcal{R}, \mathcal{O})$ **Grasp: A Unified Representation for Cross-Embodiment Dexterous Grasping**
***Zhenyu Wei\***, Zhixuan Xu\*, Jingxiang Guo, Yiwen Hou, Chongkai Gao, Zhehao Cai, Jiayu Luo, Lin Shao*
**ICRA 2025 (Best Paper Award on Robot Manipulation and Locomotion)**
**CoRL 2024 @ MAPoDeL Workshop (Best Robotics Paper Award)**

[1] **Auto-Pairing Positives through Implicit Relation Circulation for Discriminative Self-Learning**
*Bo Pang, **Zhenyu Wei**, Jingli Lin, Cewu Lu*
**TPAMI 2025 (IF: 18.6)**

## RESEARCH EXPERIENCE

**University of North Carolina at Chapel Hill**  Aug. 2025 - Present
*Ph.D. Student*  Advisor: Prof. Mingyu Ding

**Shanghai Qi Zhi Institute · Tsinghua Embodied AI Lab**  Feb. 2025 - Jul. 2025
*Research Intern*  Advisor: Prof. Huazhe Xu

**National University of Singapore · LinS Lab**  Jun. 2024 - Feb. 2025
*Research Assistant*  Advisor: Prof. Lin Shao

**Shanghai Jiao Tong University · Machine Vision and Intelligence Group**  Oct. 2022 - May 2024
*Research Intern*  Advisor: Prof. Cewu Lu

## SELECTED HONORS

- **ICRA 2025 Best Paper Award on Robot Manipulation and Locomotion** 2025
- **Best Paper Award**, ICRA 2025 @ Human-Centric Multilateral Teleoperation 2025
- Zhiyuan Outstanding Scholarship (Top 30 Undergraduates at SJTU) 2025
- Shanghai Outstanding Graduate (Top 5% of Graduates at SJTU) 2025
- **Best Robotics Paper Award**, CoRL 2024 @ MAPoDeL 2024
- Outstanding Scholarship of Computer Science Alumni Fund (Top 5% in Major) 2024
- Huawei Scholarship (Top 5% in Major) 2023
- The Tung Foundation Scholarship (Top 5% in Major) 2022
- Zhiyuan Honors Scholarship (Top 10% Students at SJTU) 2021 - 2024

## MISCELLANEOUS

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| **Language** | Chinese (native), English (TOEFL 104), Japanese (amateur) |
| **Academic Service** | Conference Reviewer for CVPR 2026, ICRA 2025 & 2026, IROS 2025, ICCV 2025 |
| | Journal Reviewer for JFR |
| **Programming** | Python, C/C++, LaTeX, Linux, Git, HTML, CSS |
| **Real Robots** | xArm6, UR5, Franka, LeapHand, GaiaHand, Dex-3, Robotiq 2F-85 |